

11.1

Given: $x = 4t^3 - 6t^2 + 2t - 1$ $x = m, t = s$
 Find: x, v, a and a at $t = 2s$

Have - $x = 4t^3 - 6t^2 + 2t - 1$
 Then $v = \frac{dx}{dt} = 12t^2 - 12t + 2$
 And $a = \frac{dv}{dt} = 24t - 12$

At $t = 2s$: $x_2 = 4(2)^3 - 6(2)^2 + 2(2) - 1$ OR $x_2 = 19m$
 $v_2 = 12(2)^2 - 12(2) + 2$ OR $v_2 = 38 \frac{m}{s}$
 $a_2 = 48(2) - 12(2)$ OR $a_2 = 60 \frac{m}{s^2}$

11.2

Given: $x = 3t^4 + 4t^3 - 7t^2 - 5t + 8$ $x = mm, t = s$
 Find: x, v, a and a at $t = 3s$

Have - $x = 3t^4 + 4t^3 - 7t^2 - 5t + 8$
 Then $v = \frac{dx}{dt} = 12t^3 + 12t^2 - 14t - 5$
 And $a = \frac{dv}{dt} = 36t^2 + 24t - 14$

At $t = 3s$: $x_3 = 3(3)^4 + 4(3)^3 - 7(3)^2 - 5(3) + 8$ OR $x_3 = 121mm$
 $v_3 = 12(3)^3 + 12(3)^2 - 14(3) - 5$ OR $v_3 = 305 \frac{mm}{s}$
 $a_3 = 36(3)^2 + 24(3) - 14$ OR $a_3 = 382 \frac{mm}{s^2}$

11.3

Given: $x = 6t^3 - 8 + 40 \cos 6t$ $x = m, t = s$
 Find: x, v, a and a at $t = 6s$

Have - $x = 6t^3 - 8 + 40 \cos 6t$
 Then $v = \frac{dx}{dt} = 12t^2 - 40 \sin 6t$
 And $a = \frac{dv}{dt} = 24t - 40 \pi^2 \cos 6t$

At $t = 6s$: $x_6 = 6(6)^3 - 8 + 40 \cos 36$ OR $x_6 = 248m$
 $v_6 = 12(6)^2 - 40 \sin 36$ OR $v_6 = 71 \frac{m}{s}$
 $a_6 = 24(6) - 40 \pi^2 \cos 36$ OR $a_6 = 383 \frac{m}{s^2}$

11.4

Given: $x = \frac{5}{2}t^3 - \frac{7}{2}t^2 - 30t + 8$ $x = ft, t = s$
 Find: t, x, a and a when $v = 0$

Have - $x = \frac{5}{2}t^3 - \frac{7}{2}t^2 - 30t + 8$
 Then $v = \frac{dx}{dt} = 5t^2 - 7t - 30$
 And $a = \frac{dv}{dt} = 10t - 7$

When $v = 0$: $5t^2 - 7t - 30 = 5(t^2 - t - 6) = 0$
 OR $t = 3s$ AND $t = -2s$ (reject) $\therefore t = 3s$

At $t = 3s$: $x_3 = \frac{5}{2}(3)^3 - \frac{7}{2}(3)^2 - 30(3) + 8$ OR $x_3 = 58.5ft$
 $a_3 = 10(3) - 7$ OR $a_3 = 23 \frac{ft}{s^2}$

11.5

Given: $x = 6t^4 - 2t^3 - 12t^2 + 3t + 3$ $x = m, t = s$
 Find: t, x, a and a when $a = 0$

Have - $x = 6t^4 - 2t^3 - 12t^2 + 3t + 3$
 Then $v = \frac{dx}{dt} = 24t^3 - 6t^2 - 24t + 3$
 And $a = \frac{dv}{dt} = 72t^2 - 12t - 24$

When $a = 0$: $72t^2 - 12t - 24 = 12(6t^2 - t - 2) = 0$
 OR $(3t - 2)(2t + 1) = 0$

OR $t = \frac{2}{3}s$ AND $t = -\frac{1}{2}s$ (reject) $\therefore t = 0.667s$
 At $t = \frac{2}{3}s$: $x_{\frac{2}{3}} = 6(\frac{2}{3})^4 - 2(\frac{2}{3})^3 - 12(\frac{2}{3})^2 + 3(\frac{2}{3}) + 3$ OR $x_{\frac{2}{3}} = 2.59m$
 $a_{\frac{2}{3}} = 72(\frac{2}{3})^2 - 12(\frac{2}{3}) - 24$ OR $a_{\frac{2}{3}} = 2.59 \frac{m}{s^2}$

11.6

Given: $x = 3t^3 - 4t^2 - 12t + 5$ $x = m, t = s$
 Find: (a) t when $v = 0$
 (b) x, a and total distance travelled when $t = 4s$

Have - $x = 3t^3 - 4t^2 - 12t + 5$
 Then $v = \frac{dx}{dt} = 9t^2 - 8t - 12$
 And $a = \frac{dv}{dt} = 18t - 8$

(a) When $v = 0$: $9t^2 - 8t - 12 = 3(3t^2 - 4t - 4) = 0$
 OR $(3t + 2)(t - 2) = 0$

OR $t = 2s$ AND $t = -\frac{2}{3}s$ (reject) $\therefore t = 2s$

(b) At $t = 4s$: $x_4 = 3(4)^3 - 4(4)^2 - 12(4) + 5$ OR $x_4 = 55m$
 $a_4 = 18(4) - 8$ OR $a_4 = 60 \frac{m}{s^2}$

First observe that $0 \leq t \leq 2s$: $v < 0$
 $t > 2s$: $v > 0$

Now - At $t = 0$: $x_0 = 5m$
 At $t = 2s$: $x_2 = 3(2)^3 - 4(2)^2 - 12(2) + 5 = -19m$



Then $x_2 - x_0 = -19 - 5 = -24m$

$x_4 - x_2 = 55 - (-19) = 74m$

\therefore Total distance travelled = $(24 + 74)m = 98m$

11.7

Given: $x = t^3 - 9t^2 + 24t - 8$ $x = m, t = s$
 Find: (a) t when $v = 0$
 (b) x and total distance travelled when $a = 0$

Have - $x = t^3 - 9t^2 + 24t - 8$
 Then $v = \frac{dx}{dt} = 3t^2 - 18t + 24$
 And $a = \frac{dv}{dt} = 6t - 18$

(a) When $v = 0$: $3t^2 - 18t + 24 = 3(t^2 - 6t + 8) = 0$
 OR $(t - 2)(t - 4) = 0$

OR $t = 2s$ AND $t = 4s$

(b) When $a = 0$: $6t - 18 = 0$ OR $t = 3s$
 At $t = 3s$: $x_3 = 3(3)^3 - 9(3)^2 + 24(3) - 8$ OR $x_3 = 10m$

First observe that $0 \leq t \leq 2s$: $v > 0$
 $2s < t < 4s$: $v < 0$

Now - At $t = 0$: $x_0 = -8m$
 At $t = 2s$: $x_2 = (2)^3 - 9(2)^2 + 24(2) - 8 = 12m$



Then $x_2 - x_0 = 12 - (-8) = 20m$

$x_3 - x_2 = 10 - 12 = -2m$

\therefore Total distance travelled = $(20 + 2)m = 22m$

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JL Elias



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Dynamics – Formulas and Problems Dietmar Gross, Wolfgang Ehlers, Peter Wriggers, Jörg Schröder, Ralf Müller, 2016-10-05 This book contains the most important formulas and more than 190 completely solved problems from Kinetics and Hydrodynamics It provides engineering students material to improve their skills and helps to gain experience in solving engineering problems Particular emphasis is placed on finding the solution path and formulating the basic equations Topics include Kinematics of a Point Kinetics of a Point Mass Dynamics of a System of Point Masses Kinematics of Rigid Bodies Kinetics of Rigid Bodies Impact Vibrations Non Inertial Reference Frames Hydrodynamics Canadiana ,1982

Advances in Swarm Intelligence Ying Tan, Yuhui Shi, Qirong Tang, 2018-06-15 The two volume set of LNCS 10941 and 10942 constitutes the proceedings of the 9th International Conference on Advances in Swarm Intelligence ICSI 2018 held in Shanghai China in June 2018 The total of 113 papers presented in these volumes was carefully reviewed and selected from 197 submissions The papers were organized in topical sections as follows theories and models of swarm intelligence ant colony optimization particle swarm optimization artificial bee colony algorithms genetic algorithms differential evolution fireworks algorithms bacterial foraging optimization artificial immune system hydrologic cycle optimization other swarm based optimization algorithms hybrid optimization algorithms multi objective optimization large scale global optimization multi agent systems swarm robotics fuzzy logic approaches planning and routing problems recommendation in social media prediction classification finding patterns image enhancement deep learning **Electrical & Electronics Abstracts** ,1994

Scientific and Technical Books and Serials in Print ,1984 *Advanced Computing in Industrial Mathematics* Krassimir Georgiev, Michail Todorov, Ivan Georgiev, 2017-02-06 This book presents recent research on Advanced Computing in Industrial Mathematics which is one of the most prominent interdisciplinary areas and combines mathematics computer science scientific computations engineering physics chemistry medicine etc Further the book presents the tools of Industrial Mathematics which are based on mathematical models and the corresponding computer codes which are used to perform virtual experiments to obtain new data or to better understand the existing experimental results The book gathers the peer reviewed papers presented during the 10th Annual Meeting of the Bulgarian Section of SIAM BGSIAM from December 21 to 22 2015 in Sofia Bulgaria *The Neurology of Business* Martin Pfiffner, 2022-09-28 This book describes the neurology of a business as a new dimension of organization and as a basis for success in a complex world Comparing organizations with living organisms it places an organization s neurology control and communication as a third dimension beside its anatomy structure and physiology process Overlooked by classical organizational theory this third dimension offsets its typical drawbacks The Neurology of Business introduces Stafford Beer s Viable System Model VSM and shows how this helps managers to diagnose discover and unleash the potential and performance lying dormant in today s enterprises The book is based on numerous consulting projects and management seminars conducted in Europe America and Asia It guides the

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